

Is Mandatory Voting Better than Voluntary Voting?

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Abstract

We investigate the welfare effects of policies that increase voter turnout in costly voting models. In a generalized costly voting model, we show that if the electorate is sufficiently large, then increasing voter turnout is generically efficient. Increasing turnout in small elections is only inefficient if the electorate is evenly divided or if there is already almost complete voter participation. Finally, we argue that the effects underlying our results are robust in a large class of endogenous participation models.

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1 Introduction

Many societies encourage voter participation in elections and meetings. In the recent 2004 U.S. elections, many states expanded the opportunities for early and absentee voting. Several other countries have tried to increase turnout by making participation in elections “mandatory”.¹ For example, the Australian parliament enacted mandatory voting in 1924, because voter turnout had dropped below 60 percent. By law, all Australian citizens over the age of 18 must register to vote and show up at a polling place on election day. A citizen who misses the election is subject to a \$15 fine.² The Australian mandatory voting law is successful in increasing voter turnout above 90%.³ Supporters of mandatory voting see voting as a civic duty similar to paying taxes, and argue that a higher level of participation increases the legitimacy of government. “The most important [argument] is that compulsory voting ensures that government does indeed represent the will of the whole population, not merely the section of the population that decides to express their opinions” (Wikipedia, <http://en.wikipedia.org/>).

Relatedly, political scientists and political commentators often deplore participation rates in US elections as “too low” and advocate steps to increase turnout (e.g. Olbermann (2002), Dean (2003) and Weiner (2004)). A more unusual proposal was the Arizona Voter Reward Act, proposing to award 1 million dollars to a randomly selected citizen who voted, with the objective to increase the participation rate.⁴ Yet, beyond the claim that higher participation would confer a greater legitimacy on the elected government, there are no solid economic arguments why increased turnout should be desirable. Providing such an argument is the main contributions of this paper.

We use a costly voting model to investigate whether policies that increase voter turnout are socially beneficial. Specifically, we address the following questions: Does fining non-voters (or, equivalently, subsidizing voters) alter election outcomes, relative to voluntary voting? If election outcomes are affected, and if subsidized voting improves social decisions, do these benefits outweigh the increased voting costs that are a consequence of higher voter turnout?

¹These include most South American countries, as well as Australia and several European and Asian countries. See, for example, Wikipedia http://en.wikipedia.org/wiki/Compulsory_voting for a list.

²All non-voters receive a letter asking them to pay the fine. Instead of paying the fine, non-voters can also provide a written excuse. Thus, the actual cost of non-voting is the minimum over the disutility of paying \$15 or writing the letter (see Weiner (2004) for details).

³There were a few experiments with mandatory voting laws before 1900 in the US. In 1896, the Supreme Court of Missouri struck down a Kansas City charter provision as unconstitutional that assessed a \$2.50 poll tax on every man twenty-one years of age or older who failed to vote in the general city election. See Dean (2003).

⁴This proposal was voted on in a November 2006 referendum and failed to get a majority.

Our model builds on the costly voting literature (Ledyard (1984), Palfrey and Rosenthal (1983), Palfrey and Rosenthal (1985), Börgers (2004), Goeree and Grosser (2007)). N citizens must decide between two candidates A and B . Each citizen's preference is private information and independently drawn from a common distribution that assigns probability α to being an A -supporter (and $1 - \alpha$ to being a B -supporter). In addition, each individual has private information about his voting cost c . The parameter α is drawn at an interim stage, so that individuals know α when they decide whether or not to vote. For example, potential voters can learn α from pre-election opinion polls. However, institutional choices (e.g., whether voting should be mandatory) cannot be conditioned on the realization of α , because institutional choices apply for a longer time period than just a single issue election, and a rule that explicitly conditions on α (say, "choose A without an election if $\alpha > \frac{1}{2}$ ") would likely lead to large controversies among A and B -supporters as to what α is.

We characterize conditions when voting should be encouraged and when voting should be discouraged, and show that the former is much more likely to occur in practice. We show that voting should be encouraged, if the expected absolute size of the two candidates' supporter groups are sufficiently different, which occurs generically if the number of citizens is large. We also show that the optimal policy is to pay a subsidy equal to the minimal voting cost as the size of the electorate goes to infinity. While we derive our main results in a simple costly voting model, we argue in Section 4 that our findings that voting should be encouraged applies more generally to endogenous participation models in which cost considerations are important at least for the marginal voters, or for leaders who can induce some followers to vote.

To understand the intuition for our results, suppose that $\alpha > 0.5$, i.e., it is more likely that A -supporters are in the majority. However, in equilibrium, the probability that candidate B wins must be sufficiently large, otherwise voters would have no incentive to participate. For this to occur, the participation rate by B supporters must exceed that of A -supporters, which, in turn, implies that the (expected) proportion of A -supporters among non-voters is even higher than α . If a particular A -supporter votes and is pivotal, then he imposes a positive externality on non-voters who support A , and a negative externality on non-voters who support B . The net change in surplus for non-voters is approximately 0.5 (the utility change for an individual citizen) times the difference between the number of A and B supporters among non-voters. This change in surplus is positive, because in expectation there are more A than B -supporters among non-voters. In contrast, the externality on voters is negative: There are two configurations in which our A supporter is pivotal. First, if the number of other A -voters equals the number of other B -voters, and second, if the number of other A -voters is one smaller than the number of other B -voters. In the first case there is no externality, while in the second case the net change in surplus is -0.5. Thus, our A supporter

increases surplus by voting, unless there are either almost no non-voters or the electorate is fairly evenly split (α close to 0.5). Subsidies encourage more A than B supporters to vote, because there are more A -supporters than B -supporters among the whole population, and in particular, among non-voters), and are therefore welfare improving.

In an important paper, Borgers (2004) has analyzed optimal voter participation policies. In his model, the expected number of A and B supporters are equal, which corresponds to the special case $\alpha = 0.5$ (with certainty) in our model. As a consequence, only the negative externality occurs in Borgers' model, implying that voluntary voting dominates mandatory voting.

The costly voting literature dates back to Ledyard (1984) and Palfrey and Rosenthal (1983), Palfrey and Rosenthal (1985). Empirical evidence confirms many comparative static predictions of the costly voting model (see Blais (2000), Shachar and Nalebuff (1999), Levine and Palfrey (2007)): In particular, minority supporters are more active in equilibrium, and the overall participation rate is higher the closer α is to 0.5. A problem with the simple costly voting model, however, is the unrealistic prediction of a zero participation rate in very large elections. More sophisticated endogenous participation models combine cost considerations with "ethical" voters (Feddersen and Sandroni (2006)) or introduce leaders, who can influence the participation decision of a large number of citizens (e.g., Shachar and Nalebuff (1999), Herrera and Martinelli (2006)). These models succeed in generating positive participation in large electorates, while preserving the nice comparative static results of the costly voting model. While we derive our results in a simple costly voting model, we argue in Section 4 that they are robust in a considerably larger class of endogenous participation models, including the ones just mentioned.

Our model is closest to Goeree and Grosser (2007), who generalize Boergers' model to allow for the ex-ante expected support of candidates to differ. In contrast to our paper, they assume that the voting cost is deterministic and equal for all voters. In this framework, they consider the effect of opinion polls that provide the electorate with better information about the expected support of candidates. They show that an opinion poll is undesirable, because it decreases expected turnout and this, as in our model, leads to a higher probability of electoral mistakes. In contrast to our paper, voting subsidies in order to increase turnout directly would be either ineffective or lead to full participation in their setup.⁵ In summary, our model can be understood as a convex combination of the costly voting models of Borgers (2004), with whom we share the assumption of stochastic voting costs, as well as the focus of the analysis on optimal participation, and Goeree and Grosser (2007), who also analyze the effects of asymmetry in the candidates' support (but focus on the informational role of polls).

⁵Goeree and Grosser (2007) do not analyze the effect of voting subsidies.

Some other recent papers study costly voting environments related to our model. Campbell (1999) shows that, if voting costs of A and B supporters are drawn from different distributions, then the candidate with the more favorable cost distribution wins almost certainly in large elections, rather than the candidate preferred by the majority. We assume that A and B supporters' cost of voting are drawn from the same distribution and therefore Campbell's effect is absent in our model.

Ghosal and Lockwood (2004) analyze a model in which voluntary participation can be inefficiently low, but the cause of this inefficiency differs from ours. In their model, each individual has both a "private value" preference for one of the politicians, and a "common value" preference to select the politician who matches the unknown state of the world. When the common value component is sufficiently important, participation by more people leads to better information aggregation, which creates a positive externality that citizens do not internalize.

In subsequent work, Taylor and Yildirim (2006) further analyze the costly voting model used in this paper and derive conditions under which the symmetric equilibrium is unique. They also derive the speed of convergence to the winning probabilities of $1/2$ as the voting population converges to infinity.

2 Model

There are N *citizens* who have the right to vote for one of two candidates, A or B . The probability α that a citizen prefers candidate A to candidate B is chosen by nature according to a probability density function $g(\alpha)$, and becomes public information before the election. For example, the public information about α could be the result of pre-election opinion polls. Preferences for candidates A and B , respectively, are then drawn independently across individuals according to probability α .

Participating in the election is costly. The cost c a citizen pays if and only if he votes is drawn independently according to probability density function $f(c)$. We assume that $f(c)$ is strictly positive on its support $[\underline{c}, \bar{c}]$, where $0 < \underline{c} < 0.5$. (If $\underline{c} > 0.5$, then it is easy to show that no citizen would ever vote). We write $F(c)$ for the corresponding cumulative distribution function. The outcome of the election is determined by majority rule. In case of a tie, each candidate wins with probability $\frac{1}{2}$. Citizen i receives a benefit normalized to 1 if his preferred candidate is elected, and 0 if the other candidate wins. We allow the government to encourage voting via a subsidy s that is paid to all voters. The subsidy s can be interpreted either as actions by government that reduce citizens' costs of electoral participation, or equivalently, as a fine that non-voters must pay. Because mandatory voting laws cannot *force* individuals to vote, but rather encourage participation through fines imposed on abstainers, our notion

of subsidized voting corresponds to how mandatory voting laws work in practice. Formally, if $P_i \in \{A, B\}$ is i 's preferred candidate, if E is the candidate who is elected, and if $v_i = 1$ and $v_i = 0$ is i 's decision whether or not to vote, then i 's utility is given by

$$u(E, v_i; P_i, c_i) = \begin{cases} 1 - v_i(c_i - s) & \text{if } E = P_i; \\ -v_i(c_i - s) & \text{if } E \neq P_i. \end{cases}$$

There are two interesting special cases encompassed in this framework of subsidized voting. First, if $s = 0$, we have a standard costly voting model; we call this case *voluntary voting*. Second, if $s \geq \bar{c}$, then all citizens vote, and we talk of *compulsory voting*.

3 Results

First note that if an individual votes, his weakly dominant strategy is to vote for his preferred candidate, and it is therefore sufficient to focus solely on an agent's participation decision. In Proposition 1, we show that there exists a symmetric equilibrium in pure strategies, which is characterized by a simple cutoff value rule for the voting costs: A -supporters choose to vote if and only if their voting costs are no higher than c_A , and B -supporters have an analogous cost threshold c_B . The proofs of all propositions are in the Appendix.

Proposition 1 *There exists a symmetric equilibrium in pure strategies that is characterized by cutoff values c_A and c_B such that individual i votes for his preferred candidate P_i if $c_i \leq c_{P_i}$, and abstains otherwise.*

While the equilibrium is the unique symmetric equilibrium in all of our numeric examples, this is very hard to prove for a general distribution of voting costs. However, in Proposition 3, we provide conditions under which symmetric equilibria are unique, and the welfare effects of subsidies analyzed in Propositions 4 and 5 hold for all symmetric equilibria.

We now analyze the welfare impact of voting subsidies. Welfare is the sum of citizens' payoffs from the elected candidate minus the voting costs of those citizens who vote. Formally, let $S(a, N, k_A, k_B)$ be the social surplus in a population with N citizens, a of whom prefer candidate A , and let k_A and k_B be the number of A and B voters.

$$S(a, N, k_A, k_B) = \begin{cases} a - k_A E(c|c \leq c_A) - k_B E(c|c \leq c_B) & \text{if } k_A > k_B \\ \frac{1}{2}a + \frac{1}{2}(N - a) - k_A E(c|c \leq c_A) - k_B E(c|c \leq c_B) & \text{if } k_A = k_B \\ N - a - k_A E(c|c \leq c_A) - k_B E(c|c \leq c_B) & \text{if } k_A < k_B \end{cases}$$

Ex-ante expected welfare is then given by

$$W = \sum_{a=0}^N \sum_{k_A=0}^a \sum_{k_B=0}^{N-a} \binom{N}{a} \alpha^a (1-\alpha)^{N-a} S(a, N, k_A, k_B) \times \binom{a}{k_A} F(c_A)^{k_A} [1 - F(c_A)]^{a-k_A} \binom{N-a}{k_B} F(c_B)^{k_B} [1 - F(c_A)]^{N-a-k_B}, \quad (1)$$

which is the probability that there are a A -supporters, k_A A -voters and k_B B -voters, multiplied with the conditional expected social surplus, and summed over all possible realizations.

Subsidy payments do not enter the definition of welfare directly, because they are transfers between citizens and therefore drop out. Instead, subsidies affect welfare indirectly by changing the participation choices, which may affect both the total voting costs incurred and the electoral outcome. Note that, if subsidies had to be raised through distortionary taxation, then the excess burden of taxation would need to be taken into account when calculating the optimal subsidy. In this case, it also matters whether voting is encouraged (through the *payment* of a subsidy to voters), or whether non-voting is discouraged (through a *penalty* that non-voters have to pay). Clearly, since penalty payments can be used to replace some distortionary taxes, they are preferable to the payment of a subsidy, which would create the need for additional distortionary taxation.

Proposition 2 considers small electorates in which all citizens vote as long as the numbers of A and B supporters are sufficiently close.

Proposition 2 *Suppose that $\bar{c} < \binom{N-1}{\lfloor (N-1)/2 \rfloor} 2^{-N}$. Then there exist $\delta > 0$ such that*

1. *For all $\alpha \in [0.5 - \delta, 0.5 + \delta]$ there exists an equilibrium with full participation. Subsidies have no effect on this equilibrium.*
2. *For $\alpha \notin [0.5 - \delta, 0.5 + \delta]$ but close to $0.5 - \delta$ and $0.5 + \delta$, there exists a symmetric equilibrium with close to full participation, for which subsidies strictly lower welfare. That is, let $W(c_1, c_2)$ denote the welfare of equilibrium (c_1, c_2) as defined in (1). Then there exists $\varepsilon > \delta$ and a continuous equilibrium selection $e: [0.5 - \varepsilon, 0.5 + \varepsilon] \times \mathbb{R}_+ \rightarrow [\underline{c}, \bar{c}]^2$, such that welfare $W(e(\alpha, s))$ is strictly decreasing in s for all $\alpha \in [0.5 - \varepsilon, 0.5 + \varepsilon] \setminus [0.5 - \delta, 0.5 + \delta]$.*

If all agents participate, then subsidies have no effect, because c_A and c_B do not change. However, once α becomes sufficiently large (or sufficiently small), some citizens no longer vote. In this case, voters impose a negative externality on other voters, which is essentially Börgers' effect. In addition, because the expected number of non-voters is small, this is the only effect that matters.

While Proposition 2 characterizes conditions under which voting subsidies may be detrimental for intermediate values of α , Proposition 3 shows that subsidies are beneficial for sufficiently high values of α .

Proposition 3 *There exists $\alpha_2 < 1$ such that there is a unique symmetric equilibrium for all $\alpha \in (\alpha_2, 1]$. Further, $\frac{\partial W}{\partial s}|_{s=0} > 0$ for all $\alpha \in (\alpha_2, 1]$, where W is welfare defined by (1). Thus, a voting subsidy, starting at $s = 0$, is welfare improving. The marginal per-capita benefit $\frac{\partial(W/N)}{\partial s}|_{s=0, \alpha=1}$ goes to 1 as $N \rightarrow \infty$.*

The intuition for the positive effect of subsidies is as follows: For α close to 1, (almost) all individuals agree which candidate they prefer. However, every citizen would like other citizen to incur the voting cost, so that issue of participation is essentially equal to the problem of private provision of a public good, with the associated free-riding problem among the majority.⁶ To provide any incentive to participate, there must be a positive probability that nobody votes. A voting subsidy increases expected participation and therefore reduces the risk of a wrong decision.

We also show, in the proof of the proposition, that the per-capita welfare effect of the subsidy converges to 1 as $N \rightarrow \infty$ (when α is close to 1). This means that subsidies are very effective, i.e., a unit of subsidy provided to voters raises *each* citizen's welfare by one unit. When N is sufficiently large, then there is a severe free-rider problem and only very few agents vote. To provide an incentive for the lowest cost agent to vote, the equilibrium probability of a mistake must be $(\underline{c} - s)$, because avoiding such a mistake is the benefit of voting. Expected average welfare in equilibrium is given by 1 minus the probability of mistake. An increase in s one-to-one reduces the probability of a mistake, without leading to a significantly higher per capita participation cost.

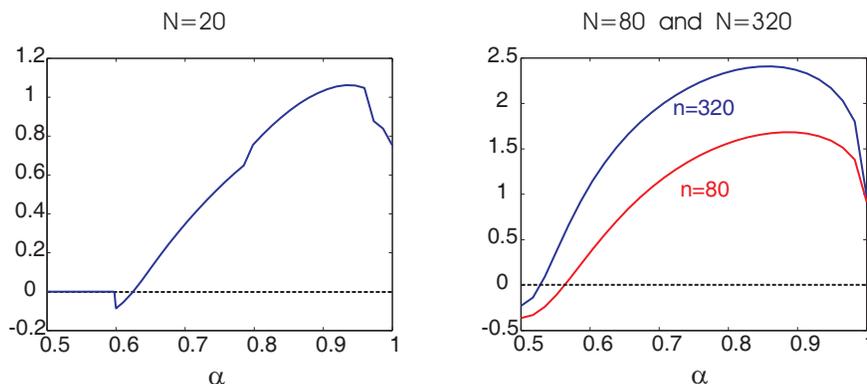


Figure 1: The Marginal Benefit of a Voting Subsidy at $s = 0$

The results of Propositions 2 and 3 are illustrated in the left panel of Figure 1, which displays the marginal benefit of a subsidy when voting cost are uniformly distributed in the interval $[0.01, 0.05]$ and $N = 20$. For α close to 0.5, all citizens vote voluntarily, so

⁶Note that citizens with *minority* preference have a much smaller incentive to free-ride, because the expected number of other citizens with the same preference is very small.

that a subsidy (or the threat of a fine for non-voters) has no effect on welfare.⁷ Around $\alpha = 0.6$, some high cost citizens start to abstain under voluntary voting. It is not helpful to induce them to vote. The reason is that the most likely scenario in which an abstainer's vote would matter is one where there is only one abstainer, in which case he is only pivotal if his vote leads to a 10-10 split of the electorate. But in that case, he imposes a net negative externality on the other voters. The negative impact on ex-ante expected welfare, however, is very limited because the probability that the subsidy increases voter participation is small, there is already almost full voter participation, and the negative externality impacts only one voter. For larger values of α , the effect identified in Proposition 3 dominates, as voluntary voting leads to a significant error probability that is decreased by a subsidy. Both the small range where the derivative is negative, and the small size of the negative derivative indicates that for most distributions G over α , subsidies are helpful.

Now consider the case that N is so large that the condition in Proposition 2 does not hold and some high cost agents abstain even if $\alpha = 0.5$. For the above parametrization this occurs for $N \geq 64$. At this point, Börger's negative externality dominates for α that are sufficiently close to 0.5, which is what happens in the right panel of Figure 1 for $N = 80$ and $N = 320$. For higher values of α , Proposition 3 applies so that subsidies increase surplus.

In the examples, a marginal subsidy is helpful as long as the distribution of α is not extremely concentrated around 0.5. Moreover, the positive effect dominates very soon, and is considerably larger in size. The intuition for this is as follows: Both the positive and the negative effect arise only if an additional voter is pivotal. However, the negative effect stems from an externality affecting other *voters*, and in a pivot situation, the number of negatively-affected voters is at most one larger than the number of positively affected ones; the expected net per capita effect is therefore very small. In contrast, the positive effect for higher values of α is due to the increase of the winning probability of the majority-preferred candidate caused by increased voter participation, which affects many non-voters.

Figure 1 also indicates that the region of values of α where subsidies are harmful decreases with N , which suggest that this region vanishes for the limit case that N goes to infinity. We now prove this result formally.

Proposition 4 *Let A_N be the set of all α such that there exists a subsidy $s > 0$ that strictly increases welfare relative to voluntary voting for all symmetric equilibria in an economy with N agents. Then $A_N \rightarrow [0, 1]$ as $N \rightarrow \infty$ (i.e., the set of limit points of sequences α_N with*

⁷The reader may wonder whether taxing voters, if feasible, would increase welfare in the full participation region to the left of $\alpha = 0.6$ of Figure 1. This may, but need not be the case. In order to have any effect on participation, the tax would have to be sufficiently large, which would deter some citizens with substantial private benefit from voting. However, because the negative externality is small (especially if the number of citizens is odd, where it is of second order), the net change in welfare is often negative.

$\alpha_N \in A_N$ for all N is $[0, 1]$.)⁸

In the proof we first show that, for any α , the probability that the wrong candidate gets elected under voluntary voting is strictly greater than 0, even as $N \rightarrow \infty$, else no citizen would have an incentive to vote. To understand the intuition, first, note that the expected number of voters must remain finite, as otherwise, no individual voter's pivot probability would justify incurring strictly positive voting costs of at least \underline{c} . Hence, both cost cutoffs that characterize the equilibrium must converge to \underline{c} . Therefore, in the limit, the probability to be pivotal must be the same for an A- and a B-supporter. We show in the proof that this implies that the winning probability for A and B must both be $1/2$.⁹ This outcome is highly inefficient, because if $\alpha > 1/2$, then the number of A-supporters exceeds that of B-supporters with probability close to 1. Thus, voluntary voting leads to a substantial mistake probability in equilibrium. Subsidies increase turnout, which lowers the mistake probability.

We prove Proposition 4 by showing that, starting from $s = 0$, a small increase in s is beneficial for given $\alpha \neq 0.5$. We now turn to the question which subsidy is actually optimal. For any finite N , this question is very hard to answer analytically. However, for $N \rightarrow \infty$, the following proposition shows that the optimal subsidy converges to \underline{c} .

Proposition 5 *Let s_N be the optimal subsidy of a society with N citizens. Then $s_N \rightarrow \underline{c}$ as $N \rightarrow \infty$.¹⁰ Moreover, subsidies strictly improve upon voluntary voting for large N .¹¹*

To gain intuition, consider a subsidy of $s = \underline{c} + \varepsilon$. Such a subsidy makes it a dominant strategy for everyone with cost below $\underline{c} + \varepsilon$ to vote, where ε is positive but small. Essentially, such a subsidy allows drawing a sample that is relatively small compared to the total population to avoid significant voting costs, but it is still sufficiently large to yield the correct decision with probability 1.

⁸More formally, let $e: [0, 1] \times \mathbb{R}_+ \times \mathbb{N} \rightarrow [\underline{c}, \bar{c}]^2$ be an arbitrary equilibrium selection, and let $W(e(\alpha, s, N))$ be the associated welfare. Let $A_N = \{\alpha \in [0, 1] | W(e(\alpha, s, N)) > W(e(\alpha, 0, N)) \text{ for some } s > 0\}$. Then $A_N \rightarrow [0, 1]$ as $N \rightarrow \infty$.

⁹Note that this result mirrors a prior result by Goeree and Grosser (2007). In their mixed strategy equilibrium, both candidates have the same probability of winning, independent of the number of citizens, while in our model, this result only obtains in the limit. The reason for the difference is that voters in Goeree and Grosser all have the same cost of voting, while in our model, costs are drawn from a distribution and the effects of voters' private information about their cost only vanish in the limit.

¹⁰More formally, let $e: [0, 1] \times \mathbb{R}_+ \times \mathbb{N} \rightarrow [\underline{c}, \bar{c}]^2$ be an arbitrary equilibrium selection, let $W(e(\alpha, s, N))$ be associated welfare, and $W^*(\alpha, N) = \sup_{s \in \mathbb{R}} W(e(\alpha, s, N))$ the maximum possible welfare. Let s^n be any convergent sequence for which W approaches the maximum welfare, i.e., $\lim_{n \rightarrow \infty} W(e(\alpha, s^n, N)) = W^*(\alpha, N)$. Then $\lim_{n \rightarrow \infty} s^n = \underline{c}$.

¹¹That is, there exists \bar{N} such that $W^*(\alpha, N) > W(e, 0, N)$ for all $N \geq \bar{N}$.

4 Robustness

4.1 Asymmetric voting costs

The result of Proposition 5 that a subsidy of $s = \underline{c} + \varepsilon$ can implement the socially optimal decision for negligible voting costs depends crucially on the assumption that both A-supporters' and B-supporters' voting costs are distributed according to the same cost distribution. Consider what happens if, instead, A-supporters' costs are distributed according to cumulative distribution function $F_A(c)$, while B-supporters' costs are distributed according to cumulative distribution function $F_B(c)$. (The difference may affect both the minimum and maximum voting cost of each type, \underline{c}_i , \bar{c}_i , as well as the distribution of voting costs in between those extremes). In fact, such a difference in voting cost distributions could be very natural if the supporters differ systematically in, say, their opportunity cost of time (e.g., if the proportion of retired and working age citizens differ among A-supporters and B-supporters).

Consider first what happens in this generalized model when the number of voters is large and no subsidy is paid. By arguments analogous to those used in the proofs of the propositions so far, the pivot probability for an A-supporter must go to $2\underline{c}_A$, and the pivot probability for a B-supporter must go to $2\underline{c}_B$. If, say, $\underline{c}_A < \underline{c}_B$, then this can only be the case if the probability that A wins is larger than the probability that B wins.¹² Note that the equilibrium winning probability is independent of the percentage of citizens who prefer A or B.¹³

For example, suppose that $\underline{c}_A = 0.01$ and $\underline{c}_B = 0.015$. Using the logic detailed in the proof of Proposition 3, we can set the right-hand side of (31) equal to $2\underline{c}_A = 0.02$, and the right-hand side of (32) equal to $2\underline{c}_B = 0.03$, and solve for $\bar{v}_A = 17.1213$, $\bar{v}_B = 7.5405$. (Here, \bar{v}_i is the expected number of voters for i . The number of voters for candidate i is Poisson distributed with \bar{v}_i as the parameter of this distribution.) This implies that the probability that candidate A wins is approximately 0.975.

Now, consider the effect of a subsidy. It is clear that a subsidy of, say, 0.07 would induce only those A-supporters with voting costs between 0.05 and 0.07 to vote. In this case, candidate A would win with certainty. Whether this is beneficial or detrimental for social welfare depends on whether the A-supporters form a majority of the electorate (i.e., $\alpha > 1/2$), and, of course, on the size of voting costs incurred because of the subsidy.

¹²To see this, note that the pivot probability for a B-supporter is larger than the pivot probability for an A-supporter if and only if the probability that there is one more A- than B-supporter is larger than the probability that there is one more B- than A-supporter. This will only be the case if the (Poisson) distribution of the number of A-supporters dominates the distribution of the number of B-supporters.

¹³The result that the equilibrium winning probability is independent of the preference distribution also obtains in the model of Campbell (1999) described in the introduction.

Let c^* be the smallest value of c such that $F_A(c) = F_B(c) > 0$. That is, c^* is either the lowest point at which the two cumulative distribution functions intersect, or, if there is no such point, then $c^* = \max(\bar{c}_A, \bar{c}_B)$. Setting the subsidy equal to $s = c^*$ guarantees that the candidate who is supported by a majority of voters wins the election, because the same proportion $F_A(c^*) = F_B(c^*)$ of A-supporters and B-supporters will choose to vote: Clearly, all voters with $c \leq c^*$ have a dominant strategy to vote, and given that infinitely many voters vote, the pivot probability is equal to zero, so that no voters with higher cost will vote.

Moreover, it is clear that $s = c^*$ is the cheapest way to guarantee a victory of the majority-preferred candidate. A subsidy of $s = c^*$ need not be the optimal subsidy, as non-trivial voting costs arise, and there is a trade-off between voting costs and probability of making the correct decision. Let $M(s)$ denote the expected gross welfare from the election outcome given a subsidy level s , i.e. $M(s) = \int_0^1 [\alpha \text{Prob}(\text{A wins}|\alpha, s) + (1 - \alpha) \text{Prob}(\text{B wins}|\alpha, s)] g(\alpha) d\alpha$. (Note that there is a unique symmetric equilibrium in which voters vote if and only if their cost parameter is not larger than s , so $M(s)$ is well defined.) Expected net welfare as a function of s is gross welfare minus aggregate voting cost, i.e.

$$W(s) = M(s) - \int \alpha g(\alpha) d\alpha \int_0^s c f_A(c) dc - \left(1 - \int \alpha g(\alpha) d\alpha\right) \int_0^s c f_B(c) dc.$$

Clearly, the second and third terms are increasing in s , as a higher subsidy will increase turnout and therefore aggregate voting costs. Since $M(\cdot)$ is maximized at c^* , it is clear that the optimal subsidy level that maximizes $W(\cdot)$ is strictly less than c^* .

Intuitively, starting from a full participation subsidy, consider lowering the subsidy slightly, and suppose that this leads to a higher percentage of A-supporters than B-supporters participating. This leads to some mistakes, that is, victories of candidate A even if α is slightly below 1/2, but the extent of the mistake is also very small in these cases (because the A-supporter minority is almost as large as the B-supporter majority). Thus, the welfare loss from making the wrong decision is a second order effect. In contrast, the cost saving from some high-cost B-supporters not participating is a first-order effect. Note, however, that the optimal subsidy can be very close to c^* , and thus (if the cumulative cost distributions of the two types do not intersect), the optimal policy may be close to compulsory voting, i.e. a subsidy (or penalty) sufficient to induce almost all citizens to vote in equilibrium.

Suppose, for example, that the voting costs of A-supporters are uniformly distributed on $[0.01, 0.02]$ and those of B-supporters are uniform on $[0.015, 0.025]$. Furthermore, let α be distributed uniformly on $[0.4, 0.6]$. Without subsidies, or with subsidies below 0.01, the probability that A wins is independent of the realized α and thus (integrating over α and taking into account the symmetry of the α -distribution), it is easy to see that the average expected utility is 0.5.

A somewhat larger subsidy now clearly diminishes welfare: A positive proportion of

A-supporters will vote, and candidate A wins with certainty. Given the symmetry of the distribution of α , this does not increase the average gross payoff of voters from the winning candidate, and causes an increase in voting costs incurred.

If $s > 0.02$, all A-supporters vote (so that A receives the votes from a fraction α of citizens), and the proportion of the population voting for B is $(1 - \alpha) \frac{s-0.015}{0.01}$. Thus, solving for α , candidate A will win whenever $\alpha \geq \frac{s-0.015}{s-0.005}$. (This implies that the minimum subsidy such that B can win satisfies $\frac{s-0.015}{s-0.005} = 0.4$, which can be solved for $s = 0.02166$). Thus,

$$W(s) = \frac{1}{0.6 - 0.4} \left[\int_{0.4}^{\frac{s-0.015}{s-0.005}} (1 - \alpha) d\alpha + \int_{\frac{s-0.015}{s-0.005}}^{0.6} \alpha d\alpha \right] - \frac{1}{2} 0.015 - \frac{1}{2} \int_{0.015}^s c \frac{1}{0.6 - 0.4} dc$$

Differentiating with respect to s and solving for s yields that the optimal subsidy in this case is approximately $s = 0.0248$, leading to a 98% participation rate of B-supporters (as well as, of course, a 100% participation of A-supporters). This example therefore shows that the optimal subsidy (or penalty for not voting) need not be small when the voting cost distributions of the two types differ, and may have a substantial rather than marginal impact on the participation rate.

4.2 Subsidies in different models of participation

We have shown that subsidizing participation is typically optimal in our costly voting model. In this section, we show that this result extends to other models of endogenous participation in elections. The empirical evidence on the general class of costly voting models (i.e., not just our version of it) is mixed. On the one hand, the costly voting model predicts that the minority supporters are more active in equilibrium which makes up for their smaller numbers (*underdog effect*). Also, in the costly voting framework, higher participation rates are expected in close elections (*competition effect*).¹⁴ These comparative static results are supported by most empirical studies.¹⁵

¹⁴The terms “underdog effect” and “competition effect” are coined by Levine and Palfrey (2007), who provide evidence from laboratory experiments for both effects. In our model, the underdog effect (for a large electorate) is an obvious consequence of the fact that the expected number of votes for A and B must be approximately equal: If $\alpha > 1/2$, this can only be the case if B-supporters vote, on average, more often than A-supporters.

In our framework, the competition effect means that, the closer α is to $1/2$, the higher is the expected equilibrium participation rate. We do not provide a formal result along these lines, and neither do Levine and Palfrey (2007) in their setup, nor any other paper that we know of. However, the competition effect holds in all of our numerical examples, as well as in those examples that Levine and Palfrey analyze.

¹⁵See Matsusaka and Palda (1993), Table 1, for a summary of empirical papers analyzing the relation between closeness of elections and participation rates. For example, in 35 of 49 regressions reviewed (in various papers), the margin of victory was a significant predictor of participation rates.

On the other hand, the simple costly voting model predicts that participation rates go to zero for large elections, which is evidently not the case. It is therefore important to analyze whether voting subsidies may still play an important role in models that can account for positive equilibrium participation rates in large elections. We first consider a model in which some voters enjoy voting and show that this gives rise to a new effect that may make subsidies beneficial. We then sketch how to extend that model to allow for endogenous participation decisions by leaders that can motivate some voters with positive voting costs to participate.

Consider first a very simple model with an infinite number of citizens. Proportion δ of the population has zero or negative voting costs (group D – *dutiful voters*), while proportion $1 - \delta$ has positive voting costs distributed on $[\underline{c}, \bar{c}]$ as in our base model (group C – *costly voters*). Furthermore, let α_D (α_C) be the probability a group D (group C) individual prefers candidate A. From an ex-ante point of view, $g(\alpha_C, \alpha_D)$ is the density from which α_C and α_D are drawn.

Clearly, if there are no subsidies, only citizens who enjoy voting (i.e., who belong to group D) vote. Therefore, candidate A wins the election if and only if $\alpha_D > 1/2$. From a social point of view, candidate A should win if and only if $\alpha \equiv \delta\alpha_D + (1 - \delta)\alpha_C > 1/2$. Hence, even if a significant group of individuals have negative voting costs, voluntary participation guarantees that the correct candidate wins only for a very small class of distributions that have the property that $\alpha_D > 1/2$ ($< 1/2$) implies that $\alpha > 1/2$ ($< 1/2$) with probability 1. More generally, the equilibrium per-capita utility under voluntary voting is

$$\int_0^1 \left[\int_{1/2}^1 [\delta\alpha_D + (1 - \delta)\alpha_C] g(\alpha_C, \alpha_D) d\alpha_D + \int_0^{1/2} [1 - \delta\alpha_D - (1 - \delta)\alpha_C] g(\alpha_C, \alpha_D) d\alpha_D \right] d\alpha_C + \delta EB, \quad (2)$$

where EB is the average benefit that voters in group D receive from voting. Clearly, paying a subsidy of only \underline{c} does not significantly increase participation and hence is unlikely to change the outcome of the election, but paying a subsidy of \bar{c} (equivalently, compulsory voting) yields a per-capita utility of

$$\int_0^1 \int_0^1 \max \{ \delta\alpha_D + (1 - \delta)\alpha_C, 1 - \delta\alpha_D - (1 - \delta)\alpha_C \} g(\alpha_C, \alpha_D) d\alpha_D d\alpha_C + \delta EB - (1 - \delta)EC, \quad (3)$$

where EC is the expected per-capita voting cost among voters with positive voting costs. Since the integral terms in (3) are generically larger than the corresponding terms in (2), compulsory voting leads to a higher welfare, provided that the average voting cost EC of the costly voters is sufficiently small.

Note that the model so far can “explain” positive participation rates by assuming that some people enjoy voting, but it cannot explain the *underdog effect* and the *competition effect*.¹⁶ Both effects are well documented, both for large scale elections (see, e.g., Blais

¹⁶In an infinitely large electorate, a citizen will vote if and only if his cost of voting is non-positive, because

(2000), Shachar and Nalebuff (1999)) and in laboratory experiments (see Levine and Palfrey (2007)). Alternative endogenous participation models also generate these effects. For example, Feddersen and Sandroni (2006) develop a model of *ethical voters* who receive a moral benefit that possibly offsets their voting costs, if they feel that they “should” vote. The ethical rule that specifies the voting cost threshold below which an individual voter “should” vote is derived endogenously, taking into account both cost considerations and the preference group’s chance of winning. While no voter is individually pivotal with positive probability in the model of Feddersen and Sandroni, a positive percentage of ethical voters participates in the election. Moreover, there is a positive probability that the minority candidate wins, and ethical minority voters are more likely to participate in equilibrium.

Shachar and Nalebuff (1999) and Herrera and Martinelli (2006) develop models with a number of “leaders” who favor either candidate A or candidate B and can decide whether to take a costly action that mobilizes a (random) number of voters to vote for their respective preferred candidate. Equilibria in these models also feature positive participation rates, a positive mistake probability and the underdog effect.

We now sketch an extension of the above model that corrects this shortcoming of the costly voting model. Suppose there are L_A “A-leaders” and L_B “B-leaders,” who each have influence over a set of measure ℓ of costly voters who support A and B, respectively. Clearly, $L_A\ell \leq \alpha_C$ and $L_B\ell \leq 1 - \alpha_C$. A leader can “mobilize” his followers by imposing (through moral pressure etc.) a cost of not voting. Without loss of generality, we can assume that all his followers vote if a leader mobilizes (otherwise, we can just decrease ℓ accordingly). A leader’s objective function is a weighted average between utility from the election outcome and the average voting costs of his followers.¹⁷ Also assume that the weight on voting costs is sufficiently small, so that a leader who knows that he can change the election outcome by mobilizing would strictly prefer to do so. Candidate A wins the election if and only if $\delta\alpha_D + (1 - \delta)\ell M_A > \delta(1 - \alpha_D) + (1 - \delta)\ell M_B$, where M_A and M_B are the number of A- and B-leaders who mobilize, respectively. Rearranging this condition, we get

$$M_A - M_B > \frac{\delta}{1 - \delta} \frac{1 - 2\alpha_D}{\ell} \equiv K. \quad (4)$$

If the expression K on the right hand side of (4) is positive, then it is the critical number by which the number of mobilizing A-leaders must exceed the number of mobilizing B-leaders in order for Candidate A to win.

the probability of being pivotal for the election outcome is zero. Note that this would even be true in large finite electorates: As soon as the expected pivot probability drops below $2\underline{c}$ (because of the many voters with negative participation costs), no voter with voting costs greater or equal to \underline{c} would participate.

¹⁷An alternative possibility that leads to qualitatively the same results is that leaders do not care about their followers’ voting costs, but face some mobilization costs.

A leader’s strategic calculations are very similar to the calculations of a costly voter in our basic model. Provided that δ is not too large (so that costly voters can, in principle, swing the election to the candidate who is not preferred by the majority of the dutiful voters), both candidates have a strictly positive chance of winning in equilibrium. If, instead, δ is large (how large depends also on the value of α_D), then only dutiful voters participate in the election and the majority among them is decisive. This model therefore can explain the fact that in presidential elections in Utah and Massachusetts, the Republican or Democratic candidate, respectively, consistently wins: The advantage of one party over the other among dutiful voters is just so large that leaders do not try to mobilize costly voters and consequently, the larger preference group wins always. In contrast, the simple costly voting model (with all voters having voting costs) would predict that Democratic and Republican presidential candidates should each have a significant probability of winning Utah or Massachusetts.

The effect of leaders on welfare relative to a model in which only dutiful voters vote can be ambiguous. On the one hand, if the majority group among dutiful voters is not equal to the majority preference group in the total population, then the presence of leaders makes it at least possible that the majority-preferred candidate wins. On the other hand, if the majority group among dutiful voters is equal to the majority preference group in the total population, then the presence of leaders introduces the possibility that the wrong candidate wins.

As in the basic model and the voluntary voting model above, it is quite conceivable that voting subsidies are desirable from a social point of view. With voting subsidies, more costly voters choose to vote, regardless of the actions of leaders. If the voting subsidy is sufficiently large to induce most citizens to vote, then the voting outcome is correct decision from a social perspective. If the average voting cost of costly voters is sufficiently small relative to the importance of the electoral decision, then subsidies are welfare enhancing in this framework.

5 Conclusion

A central theme in many texts by political scientists dealing with participation in elections (as well as in newspaper editorials) is that electoral turnout is “too low”. In this paper, we provide a theoretical framework for this idea. We show that costly voting induces suboptimal equilibrium participation and frequently leads to wrong choices. We prove that in such a world, providing incentives for citizens to vote increases the quality of electoral decisions and social welfare.

Our setup is the simplest model in which questions of costly voting can be studied: Citizens know which candidate they prefer, they only have to decide whether or not to vote,

and the voting costs are drawn from the same distribution for both A and B supporters. Extending our model to allow for incomplete information about candidates and differential voting costs for A and B supporters should reinforce our qualitative finding that voting is similar to providing a public good.

Following much of the literature, we assume that each voter's benefit from the election of his preferred candidate is normalized to one, while costs are random draws for individual voters. More generally, one could assume that each voter's benefit is also random. However, if both costs and benefits are drawn from the same distribution for A and B -supporters, the analysis for voluntary and compulsory voting is largely unchanged.

6 Appendix

Proof of Proposition 1. Let c_A be given. We construct c_B such that an individual who prefers B is indifferent between voting and not voting if $c_i = c_B$.

Consider a supporter of B . The probability that a of the remaining $N - 1$ individuals support candidate A and that k of these A supporters participate in the election, is given by

$$\text{Prob}\{\#A\text{-supporters} = a, \#A\text{-voters} = k\} = \binom{N-1}{a} \alpha^a (1-\alpha)^{N-1-a} \binom{a}{k} F(c_A)^k (1-F(c_A))^{a-k}. \quad (5)$$

If there are a supporters of A , of whom k participate in the election then our B supporter's expected benefit of voting including subsidy s but excluding voting costs is

$$\text{Benefit}(a, k) = 0.5 \left[\binom{N-a-1}{k-1} F(c_B)^{k-1} (1-F(c_B))^{N-a-k} + \binom{N-a-1}{k} F(c_B)^k (1-F(c_B))^{N-a-k-1} \right] + s. \quad (6)$$

It follows immediately that $\text{Prob}\{\#A = a, \#A\text{-voters} = k\}$ and $\text{Benefit}(a, k)$ are continuous in c_A . The expected benefit from voting for a B -supporter with voting costs c_B is

$$\text{EB}_B(c_A, c_B) = \sum_{a=0}^{N-1} \sum_{k=0}^a \text{Prob}\{\#A = a, \#A\text{-voters} = k\} \text{Benefit}(a, k), \quad (7)$$

which is continuous in c_A and c_B . Similarly, an A -supporter's gross benefit, $\text{EB}_A(c_A, c_B)$, is continuous. We now define the function $T: [\underline{c}, \bar{c}]^2 \rightarrow [\underline{c}, \bar{c}]^2$ by

$$T(c_A, c_B) = \left(\max\{\min\{\text{EB}_A(c_A, c_B), \bar{c}\}, \underline{c}\}, \max\{\min\{\text{EB}_B(c_A, c_B), \bar{c}\}, \underline{c}\} \right).$$

Clearly, T is continuous. Brouwer's fixed point theorem therefore implies that there exist c_A^*, c_B^* with $T(\bar{c}_A, \bar{c}_B) = (c_A^*, c_B^*)$. Consider c_A^* . If $\underline{c} < c_A^* < \bar{c}$ then the gross benefit of an A supporter with costs c_A^* who participates in the election is exactly c_A^* . As a consequence an A supporter with cost c_A^* is indifferent between voting and not voting, and every A supporter with a lower cost will strictly prefer to vote. Now let $c_A^* = \underline{c}$. Then $\text{EB}_A(c_A, c_B) \leq \underline{c}$. Thus, no A supporter will participate, because the probability that $c = \underline{c}$ is 0. Finally, $c_A^* = \bar{c}$ implies that all A supporters participate in the voting. Therefore, c_A^* is the cost cutoff for A supporters. Similarly, it follows that c_B^* is the equilibrium cutoff for B supporters. ■

Proof of Proposition 2. First, suppose that N is odd. Consider one particular agent, and suppose that all remaining agents vote. Then the pivot probability for that agent is

given by $\binom{N-1}{(N-1)/2} \alpha^{(N-1)/2} (1-\alpha)^{(N-1)/2}$. If the agent is pivotal, then his benefit is 0.5. Thus, $c_A = \bar{c}$ if and only if

$$\bar{c} \leq 0.5 \binom{N-1}{(N-1)/2} \alpha^{(N-1)/2} (1-\alpha)^{(N-1)/2}. \quad (8)$$

Choose $\hat{\alpha} > 0.5$ such that (8) holds with equality. Then $\delta = \hat{\alpha} - 0.5$. If $\alpha < \hat{\alpha}$ there is already full participation and subsidies are irrelevant. It remains to show that welfare is decreasing if subsidies are introduced for any $\alpha > \hat{\alpha}$ that is close to $\hat{\alpha}$.

We first show that c_A and c_B are continuous in α around $\hat{\alpha}$. We use the implicit function theorem, as generalized by Clarke (1983) to non-smooth functions (since $F(\cdot)$ is not continuously differentiable at \bar{c}).¹⁸ Because $(1 - F(c_A)) = (1 - F(c_B)) = 0$ at $\hat{\alpha}$, we can ignore terms with $(1 - F(c_A))^k$ or $(1 - F(c_B))^k$ for $k \geq 2$, because their derivatives with respect to c_A or c_B are zero. Omitting these terms, (7) implies that the benefit of a B supporter from voting is given by

$$0.5 \left[\binom{N-1}{\frac{N-1}{2}} \alpha^{\frac{N-1}{2}} (1-\alpha)^{\frac{N-1}{2}} F(c_A)^{\frac{N-1}{2}} \left[\frac{N-1}{2} F(c_B)^{\frac{N-3}{2}} (1 - F(c_B)) + F(c_B)^{\frac{N-1}{2}} \right] \right. \\ \left. + \binom{N-1}{\frac{N+1}{2}} \alpha^{\frac{N+1}{2}} (1-\alpha)^{\frac{N-3}{2}} \frac{N+1}{2} F(c_A)^{\frac{N-1}{2}} (1 - F(c_A)) F(c_B)^{\frac{N-3}{2}} \right] - c_B. \quad (9)$$

If we take derivatives from the right then $\frac{\partial F(c_A)}{\partial c_A} |_{c_A \geq \bar{c}} = \frac{\partial F(c_B)}{\partial c_B} |_{c_B \geq \bar{c}} = 0$. Thus,

$$\frac{\partial \text{EB}_A(c_A, c_B)}{\partial c_A} |_{c_A, c_B \geq \bar{c}} = -1, \quad \frac{\partial \text{EB}_A(c_A, c_B)}{\partial c_B} |_{c_A, c_B \geq \bar{c}} = 0; \\ \frac{\partial \text{EB}_B(c_A, c_B)}{\partial c_A} |_{c_A, c_B \geq \bar{c}} = 0, \quad \frac{\partial \text{EB}_B(c_A, c_B)}{\partial c_B} |_{c_A, c_B \geq \bar{c}} = -1.$$

If we take derivatives from the left then

$$\frac{\partial \text{EB}_B(c_A, c_B)}{\partial c_A} |_{c_A = \bar{c}, c_B \geq \bar{c}} = 0.5 f(\bar{c}) \frac{N-1}{2} \binom{N-1}{\frac{N-1}{2}} \alpha^{\frac{N-1}{2}} (1-\alpha)^{\frac{N-3}{2}} (1-2\alpha), \\ \frac{\partial \text{EB}_B(c_A, c_B)}{\partial c_B} |_{c_A \geq \bar{c}, c_B = \bar{c}} = -1. \quad (10)$$

By symmetry, the derivatives for A supporters are

$$\frac{\partial \text{EB}_A(c_A, c_B)}{\partial c_A} |_{c_A = \bar{c}, c_B \geq \bar{c}} = -1, \\ \frac{\partial \text{EB}_A(c_A, c_B)}{\partial c_B} |_{c_A \geq \bar{c}, c_B = \bar{c}} = -0.5 f(\bar{c}) \frac{N-1}{2} \binom{N-1}{\frac{N-1}{2}} \alpha^{\frac{N-3}{2}} (1-\alpha)^{\frac{N-1}{2}} (1-2\alpha) \quad (11)$$

¹⁸Theorem 7.1.1 of Clarke (1983) (earlier proved in Clarke (1976)) establishes the inverse function theorem for Lipschitzian functions, and the subsequent (unnumbered) corollary proves the implicit function theorem. Note that the uniqueness of the implicit function, which is not explicitly stated in the corollary, follows immediately from Theorem 7.1.1.

Thus, the determinant of right-hand derivatives is strictly positive. Similarly, it follows that the matrix of derivatives has full rank for any combination of left and right derivatives, which implies that c_A and c_B are continuous functions of α .

Consider α that is marginally greater than $\hat{\alpha}$. If all agents participate, then a particular citizen is pivotal if the number of A - and B -voters is the same among the remaining voters. If our particular citizen votes for candidate A , then the total benefit of all other A -voters increases by $(N-1)/4$, while the benefit to B voters is reduced by exactly the same amount. A subsidy would turn our citizen from a non-voter to a voter if and only if the private benefit of the person equals his voting costs, i.e., if the person's net-benefit from voting is zero. Thus, if all agents participate, there is no effect on surplus.

Now suppose that one of the remaining agents does not vote. Then a particular A supporter is pivotal if and only if there are $(N-3)/2$ A -voters and $(N-1)/2$ B -voters among the remaining agents. Thus, the net-change in benefit to these voters is -0.5 if our A supporter participates. As above, if a subsidy would induce our A -supporter to vote, then the private benefit is zero. Thus, the subsidy would lower surplus.

Note that we can ignore the effects when two or more agents do not participate, because this event is on the order of $(1 - F(c_A))^2$ and $(1 - F(c_B))^2$, while the above effect is of the order $(1 - F(c_A))$ and $(1 - F(c_B))$, and $F(c_A)$, $F(c_B)$ are close to 1.

The proof for even N is similar. With an even number of agents and full participation in the election, a particular person person, say an A supporter, is pivotal if there are $(N-3)/2$ A -supporters and $(N-1)/2$ B supporters, which implies a negative externality. Again, all higher order terms can be ignored. ■

Proof of Proposition 3. Let $\alpha = 1$. Then an A -supporter is indifferent between voting and not voting if

$$[1 - F(c_A)]^{N-1} \frac{1}{2} = c_A - s. \quad (12)$$

Since the left-hand side is non-increasing in c_A and the right-hand side is increasing in c_A , there exists a unique value of c_A that satisfies (12). Furthermore, for $s < \bar{c}$, this unique symmetric equilibrium at $\alpha = 1$ satisfies $\underline{c} < c_A < \bar{c}$.

Applying the implicit function theorem yields

$$\frac{dc_A}{ds} = \frac{2}{2 + (N-1)f(c_A)[1 - F(c_A)]^{N-2}} > 0. \quad (13)$$

Substituting $a = N$, $k_B = 0$, and $\alpha = 1$ in (1) yields

$$\begin{aligned} W &= \frac{N}{2}(1 - F(c_A))^N + \sum_{k_A=1}^N \left(N - k_A E[c|c \leq c_A] \right) \binom{N}{k_A} F(c_A)^{k_A} (1 - F(c_A))^{N-k_A} \\ &= N \left[1 - \frac{1}{2}(1 - F(c_A))^N - \int_{\underline{c}}^{c_A} cf(c) dc \right]. \end{aligned} \quad (14)$$

Taking the derivative of (14) with respect to s and using (12) yields

$$\frac{\partial W}{\partial s}\Big|_{s=0} = f(c_A)N(N-1)c_A \frac{dc_A}{ds} > 0, \quad (15)$$

which proves that subsidies increase welfare at $\alpha = 1$. Finally, using (12), (13) and the fact that $c_A \rightarrow \underline{c}$ for $N \rightarrow \infty$, implies that the derivative of per-capita surplus, $\frac{1}{N} \frac{\partial W}{\partial s}\Big|_{s=0}$, converges to 1 as $N \rightarrow \infty$.

Next, we prove that equilibrium is unique in a neighborhood of $\alpha = 1$ and that the equilibrium values of c_A and c_B are continuous in α .

First, consider a sequence indexed by i with $\alpha_i \rightarrow 1$ as $i \rightarrow \infty$, and let c_A^i, c_B^i , be the corresponding equilibrium cost cutoffs. Then, by compactness, there exist subsequences that converge to some cost levels \hat{c}_A and \hat{c}_B . Continuity of the expected voting benefits (7) implies that \hat{c}_A, \hat{c}_B is an equilibrium for $\alpha = 1$. Because the equilibrium at $\alpha = 1$ is unique, it follows that for any neighborhood \mathfrak{U} of the $\alpha = 1$ equilibrium (c_A, c_B) , there exists an $\hat{\alpha} < 1$ such that all equilibria for $\alpha \geq \hat{\alpha}$ are in \mathfrak{U} . Using the implicit function theorem we can then establish uniqueness of equilibria in a neighborhood of $\alpha = 1$. For $\alpha > 1$ we define the expected benefit to be equal to that at $\alpha = 1$. Because the expected benefit functions are non-smooth at $\alpha = 1$, we again use Clarke (1983).

Since we can ignore all terms $(1 - F(c_B))$, (7) implies that at an $\alpha = 1$ equilibrium

$$\frac{1}{2} (1 - F(c_A))^{N-1} - c_A = 0 \quad (16)$$

$$\frac{1}{2} \left[(1 - F(c_A))^{N-1} + (N-1)F(c_A)(1 - F(c_A))^{N-2} \right] - c_B = 0. \quad (17)$$

The derivative of (16) with respect to c_A is $-0.5(N-1)f(c_A)[(1 - F(c_A))]^{N-2} - 1$ and with respect to c_B is 0. The derivatives of (17) from are $-0.5(N-1)(N-2)f(c_A)[(1 - F(c_A))]^{N-3} - 1$ and -1 . Thus, the matrix of derivatives has full rank. Clarke (1983) therefore implies that there exists a unique equilibrium in a neighborhood of $\alpha = 1$, with cutoffs c_A and c_B that are continuous in α .

Finally, $\frac{\partial W}{\partial s}\Big|_{s=0} > 0$ in a neighborhood of $\alpha = 1$, since the derivative of (14) with respect to α is continuous in c_A and c_B . ■

Lemma 1 *Suppose that $\underline{c} > 0$. Then, in any equilibrium, the expected number of A and B voters, $\bar{v}_A(N)$ and $\bar{v}_B(N)$, are bounded away from ∞ , i.e., there exists an M such that $\bar{v}_A(N), \bar{v}_B(N) \leq M$ for all $N \in \mathbb{N}$.*

Proof of Lemma 1. The strategy of the proof is to show that if the expected number of voters goes to infinity as $N \rightarrow \infty$ then the pivot probabilities go to zero. This provides a contradiction because the voting costs c are always strictly positive, i.e., $c \geq \underline{c} > 0$.

First, however, we show that the pivot probabilities go to zero if the expected number of voters—conditional on a_n and b_n being the realized number of A and B supporters—converges to infinity as the size of electorate goes to infinity. To do this, we analyze the limit distribution of the difference in the number of A and B voters.

Let a_n and b_n be the number of A and B supporters, and let $N_n = a_n + b_n$ be the number of citizens. Let $Y_i^{a_n, b_n}$ be a random variable that assumes the value 1 if A -supporter i participates in the election, and is 0 otherwise. Define $Z_i^{a_n, b_n}$ analogously for B supporters. Care must be taken in applying the central limit theorem, because $Y_i^{a_n, b_n}$ and $Z_i^{a_n, b_n}$ converge to zero a.e., as a_n and $b_n \rightarrow \infty$.¹⁹

Claim 1. Let $a_n, b_n \in \mathbb{N}$ such that $\lim_{n \rightarrow \infty} a_n F(c_A(a_n)) = \lim_{n \rightarrow \infty} b_n F(c_B(b_n)) = \infty$, where $N_n = a_n + b_n$. Furthermore, suppose that $\limsup_{n \rightarrow \infty} c_A(N_n) < \bar{c}$ and $\limsup_{n \rightarrow \infty} c_B(N_n) < \bar{c}$. Then

$$\lim_{n \rightarrow \infty} P \left(\left\{ \frac{\sum_{i=1}^{a_n} Y_i^{a_n, b_n} - \sum_{i=1}^{b_n} Z_i^{a_n, b_n} - a_n F(c_A(N_n)) + b_n F(c_B(N_n))}{\sqrt{a_n \text{var}[Y_i^{a_n, b_n}] + b_n \text{var}[Z_i^{a_n, b_n}]}} \leq \lambda \right\} \right) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\lambda} e^{-\frac{x^2}{2}} dx, \quad (18)$$

where the convergence is uniform in λ .

Let $C_n = \sum_{i=1}^{a_n} E[|Y_i^{a_n, b_n} - F(c_A(N_n))|^{2+\delta}] + \sum_{i=1}^{b_n} E[|Z_i^{a_n, b_n} - F(c_B(N_n))|^{2+\delta}]$, for some $\delta > 0$. According to Theorem 4.4 in Chapter 4 of Doob (1990) it is sufficient to check that

$$\lim_{n \rightarrow \infty} \frac{C_n}{\left(a_n \text{var}[Y_i^{a_n, b_n}] + b_n \text{var}[Z_i^{a_n, b_n}] \right)^{1+\delta/2}} = 0. \quad (19)$$

Recall that $Y_i^{a_n, b_n}$ and $Z_i^{a_n, b_n}$ assume the value 1 with probabilities $F(c_A(N_n))$ and $F(c_B(N_n))$, respectively; and the value 0 otherwise. Thus, $\text{var}[Y_i^{a_n, b_n}] = F(c_A(N_n))(1 - F(c_A(N_n)))$ and

¹⁹In fact, the distinction between this result and that in Lemma 2 is as follows. Here, we show that if the expected number of voters were to go to infinity, then the limit distribution would be normal (which, as shown below, leads to a contradiction). In contrast, the Poisson limit distribution in Lemma 2 is compatible with strictly positive voting costs.

$\text{var}[Z_i^{a_n, b_n}] = F(c_B(N_n))(1 - F(c_B(N_n)))$. Consequently,

$$\begin{aligned}
& \lim_{n \rightarrow \infty} \frac{C_n}{\left(a_n \text{var}[Y_i^{a_n, b_n}] + b_n \text{var}[Z_i^{a_n, b_n}]\right)^{1+\delta/2}} \\
& \leq \lim_{n \rightarrow \infty} \frac{\sum_{i=1}^{a_n} E[|Y_i^{a_n, b_n} - F(c_A(N_n))|^{2+\delta}]}{\left(a_n \text{var}[Y_i^{a_n, b_n}]\right)^{1+\delta/2}} + \lim_{n \rightarrow \infty} \frac{\sum_{i=1}^{b_n} E[|Z_i^{a_n, b_n} - F(c_B(N_n))|^{2+\delta}]}{\left(b_n \text{var}[Z_i^{a_n, b_n}]\right)^{1+\delta/2}} \\
& = \lim_{n \rightarrow \infty} \frac{a_n F(c_A(N_n))(1 - F(c_A(N_n))) \left[(1 - F(c_A(N_n)))^{1+\delta} + F(c_A(N_n))^{1+\delta}\right]}{\left[a_n F(c_A(N_n))(1 - F(c_A(N_n)))\right]^{1+\delta/2}} \\
& \quad + \lim_{n \rightarrow \infty} \frac{b_n F(c_B(N_n))(1 - F(c_B(N_n))) \left[(1 - F(c_B(N_n)))^{1+\delta} + F(c_B(N_n))^{1+\delta}\right]}{\left[b_n F(c_B(N_n))(1 - F(c_B(N_n))))\right]^{1+\delta/2}} \\
& = \lim_{n \rightarrow \infty} \frac{(1 - F(c_A(N_n)))^{1+\delta} + F(c_A(N_n))^{1+\delta}}{\left[a_n F(c_A(N_n))(1 - F(c_A(N_n))))\right]^{\delta/2}} + \lim_{n \rightarrow \infty} \frac{(1 - F(c_B(N_n)))^{1+\delta} + F(c_B(N_n))^{1+\delta}}{\left[b_n F(c_B(N_n))(1 - F(c_B(N_n))))\right]^{\delta/2}} = 0,
\end{aligned}$$

as, by assumption, $\lim_{n \rightarrow \infty} a_n F(c_A(N_n)) = \lim_{n \rightarrow \infty} b_n F(c_B(N_n)) = \infty$, and $\limsup_{n \rightarrow \infty} c_A(N_n) < \bar{c}$ and $\limsup_{n \rightarrow \infty} c_B(N_n) < \bar{c}$. Thus, condition (19) is satisfied, proving claim 1.

Claim 2. Suppose that the assumptions of Claim 1 are satisfied. Let $\text{Piv}^A(a_n, b_n)$ and $\text{Piv}^B(a_n, b_n)$ the pivot probability of an A and B supporter given that the number of A and B supporters is a_n and b_n . Then

$$\lim_{n \rightarrow \infty} \text{Piv}^A(a_n, b_n) = \lim_{n \rightarrow \infty} \text{Piv}^B(a_n, b_n) = 0, \quad (20)$$

Define

$$q = \lim_{n \rightarrow \infty} \frac{a_n F(c_A(N_n)) - b_n F(c_B(N_n))}{\sqrt{a_n \text{var}[Y_i^{a_n, b_n}] + b_n \text{var}[Z_i^{a_n, b_n}]}}. \quad (21)$$

Note that we allow for the possibility that q is negative or positive infinity. Furthermore, we can assume without loss of generality that the sequence converges. Otherwise, we can take a converging subsequence. Let $\varepsilon > 0$ be arbitrary. Then there exists $\lambda > 0$ such that

$$\frac{1}{\sqrt{2\pi}} \int_{q-\lambda}^{q+\lambda} e^{-\frac{x^2}{2}} dx < \varepsilon. \quad (22)$$

Furthermore,

$$\lim_{n \rightarrow \infty} \sqrt{a_n \text{var}[Y_i^{a_n, b_n}] + b_n \text{var}[Z_i^{a_n, b_n}]} = \infty. \quad (23)$$

This follows again because $\text{var}[Y_i^{a_n, b_n}] = F(c_A(N_n))(1 - F(c_A(N_n)))$ and $\text{var}[Z_i^{a_n, b_n}] = F(c_B(N_n))(1 - F(c_B(N_n)))$, and because $a_n F(c_A(N_n))$ and $b_n F(c_B(N_n))$ converge to ∞ while $(1 - F(c_A(N_n)))$ and $(1 - F(c_B(N_n)))$ remain positive.

Note that if an agent is pivotal in the election then $\sum_{i=1}^{a_n} Y_i^{a_n, b_n} - \sum_{i=1}^{b_n} Z_i^{a_n, b_n} \in \{-1, 0, 1\}$. Thus, (23), and (21) imply that for sufficiently large n , a necessary condition for being pivotal is that

$$q - \lambda \leq \frac{\sum_{i=1}^{a_n} Y_i^{a_n, b_n} - \sum_{i=1}^{b_n} Z_i^{a_n, b_n} - a_n F(c_A(N_n)) + b_n F(c_B(N_n))}{\sqrt{a_n \text{var}[Y_i^{a_n, b_n}] + b_n \text{var}[Z_i^{a_n, b_n}]}} \leq q + \lambda. \quad (24)$$

Thus, (22), (24), and claim 1 imply that the probability of being pivotal is less than ε , proving claim 2.

Suppose, by way of contradiction, that there exists a subsequence of voting games N_n , $n \in \mathbb{N}$ such that $\lim_{n \rightarrow \infty} v_A(N_n) = \lim_{n \rightarrow \infty} v_B(N_n) = \infty$ (the case where the expected number of one type of voter remains finite is similar and omitted). Then, because the expected number of A and B voters are given by $\bar{v}_A(N) = F(c_A(N))\alpha N$ and $\bar{v}_B(N) = F(c_B(N))(1 - \alpha)N$, respectively, we have

$$\lim_{n \rightarrow \infty} F(c_A(N_n))N_n = \infty, \text{ and } \lim_{n \rightarrow \infty} F(c_B(N_n))N_n = \infty. \quad (25)$$

The law of large numbers implies that $\lim_{n \rightarrow \infty} a_n/N = \alpha$ and $\lim_{n \rightarrow \infty} b_n/N = (1 - \alpha)$ for a.e. sequence of realizations a_n and b_n . Furthermore, we can assume that $c_A(N_n)$ and $c_B(N_n)$ remain bounded away from \bar{c} . Otherwise, all agents participate and it is immediate that the pivot probability converges to zero. Thus, (20) holds a.e. As a consequence, Lebesgue's dominated convergence Theorem implies that the (unconditional) pivot probability converges to zero, a contradiction, since then, each citizen would be better off not voting. ■

Lemma 2 *Suppose that $\underline{c} > 0$. Then, in any equilibrium, the probability that candidate A wins the election under voluntary voting converges to $\frac{1}{2}$ as $N \rightarrow \infty$.*

Proof of Lemma 2. Lemma 1 implies that there exists a sequence of voting games N_n , $n \in \mathbb{N}$ with $\lim_{n \rightarrow \infty} \bar{v}_A(N_n) = \bar{v}_A$ and $\lim_{n \rightarrow \infty} \bar{v}_B(N_n) = \bar{v}_B$. Let a_n and b_n be the realized number of A and B supporters when there are N_n citizens. Then the law of large numbers implies that $\lim_{n \rightarrow \infty} a_n/N_n = \alpha$, for a.e. realization of A and B supporters. We first prove that $\sum_{i=1}^{a_n} Y_i^{a_n, b_n}$ and $\sum_{i=1}^{b_n} Z_i^{a_n, b_n}$ converge to Poisson distributions.

The expected number of A voters, given that there are a_n supporters of A , is $\bar{v}_A(N_n|a_n) = a_n F(c_A(N_n))$. Thus,

$$\begin{aligned} & \binom{a_n}{k} F(c_A(N_n))^k (1 - F(c_A(N_n)))^{a_n - k} \\ &= \frac{(a_n - 1) \dots (a_n - k + 1) \bar{v}_A(N_n|a_n)^k}{a_n^{k-1} k!} \left(1 - \frac{\bar{v}_A(N_n|a_n)}{a_n}\right)^{a_n - k}. \end{aligned} \quad (26)$$

Note that

$$\lim_{N \rightarrow \infty} \frac{\bar{v}_A(N_n | a_n)}{\bar{v}_A(N_n)} = \lim_{N \rightarrow \infty} \frac{a_n F(c_A(N_n))}{\alpha N F(c_A(N_n))} = 1, \quad (27)$$

because a_n/N converges to α . This implies $\lim_{n \rightarrow \infty} \bar{v}_A(N_n | a_n) = \bar{v}_A$. Thus, (26) and (27) imply

$$\lim_{n \rightarrow \infty} P(\{\#A\text{-voters} = k\} | \{\#A\text{-supporters} = a_n\}) = \frac{\bar{v}_A^k}{k!} e^{-\bar{v}_A},$$

for a.e. sequence of realizations of a_n . Taking the expectation over all realizations a_n and using Lebesgue's dominated convergence theorem implies

$$\lim_{n \rightarrow \infty} P(\{\#A\text{-voters} = k\} | N_n) = \frac{\bar{v}_A^k}{k!} e^{-\bar{v}_A}, \quad (28)$$

where the convergence is uniform in k . Similarly, $\lim_{n \rightarrow \infty} P(\{\#B\text{-voters} = k\} | N_n) = \frac{\bar{v}_B^k}{k!} e^{-\bar{v}_B}$. An A supporter with cost c_i votes if and only if

$$\frac{1}{2} P(\#A\text{-voters} - \#B\text{-voters} \in \{0, -1\} | N_n) \geq c_i, \quad (29)$$

where $P(\#A\text{-voters} - \#B\text{-voters} \in \{0, -1\} | N_n)$ is the probability that candidate A gets either one less vote or the same number of votes as candidate B , given that there are N_n individuals. Thus, (28) implies

$$\lim_{n \rightarrow \infty} P(\#A\text{-voters} - \#B\text{-voters} \in \{0, -1\} | N_n) = \sum_{i=0}^{\infty} \frac{\bar{v}_A^i}{i!} e^{-\bar{v}_A} \left(\frac{\bar{v}_B^i}{i!} e^{-\bar{v}_B} + \frac{\bar{v}_B^{i+1}}{(i+1)!} e^{-\bar{v}_B} \right), \quad (30)$$

By formula 9.6.10 in Abramowitz and Stegun (1965) (see also Myerson (2000)), we get

$$\lim_{n \rightarrow \infty} P(\#A\text{-voters} - \#B\text{-voters} \in \{0, -1\} | N_n) = \sqrt{\frac{\bar{v}_A}{\bar{v}_B}} \left(\frac{I_1(2\sqrt{\bar{v}_A \bar{v}_B})}{e^{\bar{v}_A + \bar{v}_B}} + \frac{I_0(2\sqrt{\bar{v}_A \bar{v}_B})}{e^{\bar{v}_A + \bar{v}_B}} \right), \quad (31)$$

where I_k is a modified Bessel function. Similarly, the pivot probability for a B supporter is

$$\lim_{n \rightarrow \infty} P(\#A\text{-voters} - \#B\text{-voters} \in \{0, 1\} | N_n) = \sqrt{\frac{\bar{v}_B}{\bar{v}_A}} \left(\frac{I_1(2\sqrt{\bar{v}_A \bar{v}_B})}{e^{\bar{v}_A + \bar{v}_B}} + \frac{I_0(2\sqrt{\bar{v}_A \bar{v}_B})}{e^{\bar{v}_A + \bar{v}_B}} \right). \quad (32)$$

As $n \rightarrow \infty$ both pivot probabilities in (31) and (32) must converge to $2\underline{c}$, by (29) and Lemma 1. Thus,

$$\sqrt{\frac{\bar{v}_A}{\bar{v}_B}} \left(\frac{I_1(2\sqrt{\bar{v}_A \bar{v}_B})}{e^{\bar{v}_A + \bar{v}_B}} + \frac{I_0(2\sqrt{\bar{v}_A \bar{v}_B})}{e^{\bar{v}_A + \bar{v}_B}} \right) = \sqrt{\frac{\bar{v}_B}{\bar{v}_A}} \left(\frac{I_1(2\sqrt{\bar{v}_A \bar{v}_B})}{e^{\bar{v}_A + \bar{v}_B}} + \frac{I_0(2\sqrt{\bar{v}_A \bar{v}_B})}{e^{\bar{v}_A + \bar{v}_B}} \right). \quad (33)$$

However, since the Bessel function I_1 is never zero, (33) implies that $\bar{v}_A = \bar{v}_B$, i.e., in the limit the number of A and B voters are drawn from the same Poisson distribution. As a

consequence, each candidate wins with probability $\frac{1}{2}$, independent of α . This proves the result since the winning probability is independent of the sequence N_n that was chosen. ■

Proof of Proposition 4. Lemma 2 implies that the wrong candidate is elected with probability 0.5 as $N \rightarrow \infty$. Thus, expected per-capita surplus under voluntary voting converges to 0.5.

Now consider a subsidy $s = \underline{c} + \varepsilon$. Then the number of voters goes to infinity as $N \rightarrow \infty$, because at least all citizens with costs $c \leq \underline{c} + \varepsilon$ vote. Thus, the pivot probability goes to zero, which implies that $c_A, c_B \rightarrow \underline{c} + \varepsilon$. As a consequence, if $\alpha \neq 0.5$, then the majority candidate wins with probability 1 as $N \rightarrow \infty$. Thus, ex-ante expected per-capita surplus converges to $\max\{\alpha, (1 - \alpha)\} - \int_{\underline{c}}^{\underline{c} + \varepsilon} c dF(c)$. Since ε can be chosen arbitrarily, the expected surplus given the subsidy exceeds the expected surplus from voluntary voting. As a consequence $[0, 1]$ is the set of limit points of sequences $\alpha_N \in A_N$. ■

Proof of Proposition 5. Let $S_{N,s}(\alpha)$ be the ex-ante expected surplus, given N citizens and a subsidy s . The proof of Proposition 4 implies that $\lim_{N \rightarrow \infty} S_{N,s}(\alpha) = \max\{\alpha, (1 - \alpha)\} - \int_{\underline{c}}^{\underline{c} + s} c dF(c)$, for a.e. α . Thus, $\lim_{N \rightarrow \infty} \int S_{N,s} g(\alpha) d\alpha = \int \max\{\alpha, (1 - \alpha)\} g(\alpha) d\alpha - \int_{\underline{c}}^{\underline{c} + s} c dF(c)$ by Lebesgue's dominated convergence theorem. If $s \downarrow \underline{c}$, we can therefore get arbitrarily close to the first best. In contrast, if $s \geq \gamma > \underline{c}$, then there remains a loss of at least $\int_{\underline{c}}^{\underline{c} + \gamma} c dF(c)$ in the limit. Similarly, if $s \leq \gamma < c$, then Lemma 2 implies a strictly positive probability that the wrong candidate is elected when N is large, and expected surplus is again bounded away from the first best. Thus, $s_N \rightarrow \underline{c}$. ■

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