

Quantile Regression for Longitudinal Data

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Classical Linear Fixed/Random Effects Model

Consider the model,

$$y_{ij} = \mathbf{x}_{ij}^T \boldsymbol{\beta} + \alpha_i + u_{ij} \quad j = 1, \dots, m_i, \quad i = 1, \dots, n,$$

or

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\boldsymbol{\alpha} + \mathbf{u}.$$

The matrix \mathbf{Z} represents an incidence matrix that identifies the n distinct individuals in the sample. If \mathbf{u} and $\boldsymbol{\alpha}$ are independent Gaussian vectors with $\mathbf{u} \sim \mathcal{N}(\mathbf{0}, \mathbf{R})$ and $\boldsymbol{\alpha} \sim \mathcal{N}(\mathbf{0}, \mathbf{Q})$. Observing that $\mathbf{v} = \mathbf{Z}\boldsymbol{\alpha} + \mathbf{u}$ has covariance matrix $\text{E}\mathbf{v}\mathbf{v}^T = \mathbf{R} + \mathbf{Z}\mathbf{Q}\mathbf{Z}^T$, we can immediately deduce that the minimum variance unbiased estimator of $\boldsymbol{\beta}$ is,

$$\hat{\boldsymbol{\beta}} = (\mathbf{X}^T (\mathbf{R} + \mathbf{Z}\mathbf{Q}\mathbf{Z}^T)^{-1} \mathbf{X})^{-1} \mathbf{X}^T (\mathbf{R} + \mathbf{Z}\mathbf{Q}\mathbf{Z}^T)^{-1} \mathbf{y}.$$

A Penalty Interpretation of $\hat{\beta}$

Proposition. $\hat{\beta}$ solves $\min_{(\alpha, \beta)} \|y - X\beta - Z\alpha\|_{R^{-1}}^2 + \|\alpha\|_{Q^{-1}}^2$, where $\|x\|_A^2 = x^\top Ax$.

Proof.

Differentiating we obtain the normal equations,

$$X^\top R^{-1} X \hat{\beta} + X^\top R^{-1} Z \hat{\alpha} = X^\top R^{-1} y$$

$$Z^\top R^{-1} X \hat{\beta} + (Z^\top R^{-1} Z + Q^{-1}) \hat{\alpha} = Z^\top R^{-1} y$$

Solving, we have $\hat{\beta} = (X^\top \Omega^{-1} X)^{-1} X^\top \Omega^{-1} y$ where

$$\Omega^{-1} = R^{-1} - R^{-1} Z (Z^\top R^{-1} Z + Q^{-1})^{-1} Z^\top R^{-1}.$$

But $\Omega = R + ZQZ^\top$, see e.g. Rao(1973, p 33.). □

This result has a long history: Henderson(1950), Goldberger(1962), Lindley and Smith (1972), etc.

Quantile Regression with Fixed Effects

Suppose that the conditional quantile functions of the response of the j th observation on the i th individual y_{ij} takes the form:

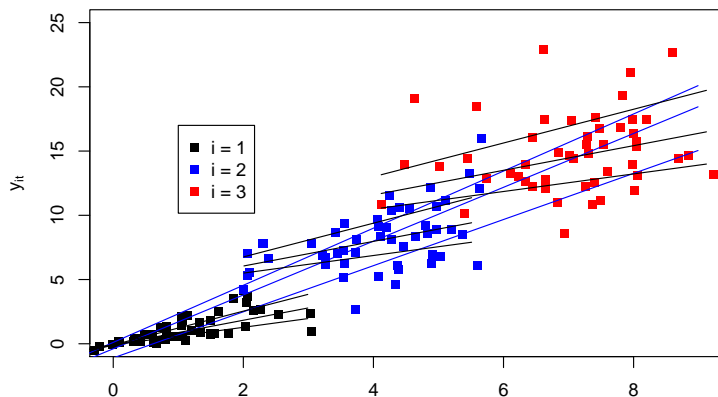
$$Q_{y_{ij}}(\tau|x_{ij}) = \alpha_i + x_{ij}^\top \beta(\tau) \quad j = 1, \dots, m_i, \quad i = 1, \dots, n.$$

In this formulation the α 's have a pure location shift effect on the conditional quantiles of the response. The effects of the covariates, x_{ij} are permitted to depend upon the quantile, τ , of interest, but the α 's do not. To estimate the model for several quantiles simultaneously, we propose solving,

$$\min_{(\alpha, \beta)} \sum_{k=1}^q \sum_{j=1}^n \sum_{i=1}^{m_i} w_k \rho_{\tau_k}(y_{ij} - \alpha_i - x_{ij}^\top \beta(\tau_k))$$

Note that the usual between/within transformations are not permitted.

Penalized Quantile Regression with Fixed Effects



Time invariant, individual specific intercepts are quantile independent;
slopes are quantile dependent.

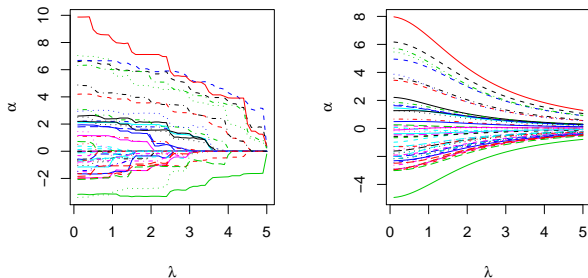
Penalized Quantile Regression with Fixed Effects

When n is large relative to the m_i 's shrinkage may be advantageous in controlling the variability introduced by the large number of estimated α parameters. We will consider estimators solving the penalized version,

$$\min_{(\alpha, \beta)} \sum_{k=1}^q \sum_{j=1}^n \sum_{i=1}^{m_i} w_k \rho_{\tau_k}(y_{ij} - \alpha_i - x_{ij}^T \beta(\tau_k)) + \lambda \sum_{i=1}^n |\alpha_i|.$$

For $\lambda \rightarrow 0$ we obtain the fixed effects estimator described above, while as $\lambda \rightarrow \infty$ the $\hat{\alpha}_i \rightarrow 0$ for all $i = 1, 2, \dots, n$ and we obtain an estimate of the model purged of the fixed effects. In moderately large samples this requires sparse linear algebra. Example R code is available from my webpages.

Shrinkage of the Fixed Effects



Shrinkage of the fixed effect parameter estimates, $\hat{\alpha}_i$. The left panel illustrates an example of the ℓ_1 shrinkage effect. The right panel illustrates an example of the ℓ_2 shrinkage effect.

Dynamic Panel Models and IV Estimation

Galvao (2010) considers dynamic panel models of the form:

$$Q_{y_{it}}(\tau|y_{i,t-1}, x_{it}) = \alpha_i + \gamma(\tau)y_{i,t-1} + x_{it}^T\beta(\tau) \quad t = 1, \dots, T_i, \quad i = 1, \dots, n.$$

In “short” panels estimation suffers from the same bias problems as seen in least squares estimators Nickel (1981) Hsiao and Anderson (1981); using the IV estimation approach of Chernozhukov and Hansen (2004) this bias can be reduced.